



Background

To bring convenience, accuracy, and modern-style to the tuning process for amateur and professional guitarists. The **handheld automatic tuner** will be designed to work in very noisy environments.

Project Goal/ Device Functionality

Create a handheld automatic guitar tuner that works in noisy environments with great accuracy. Designed for the following method of operation:

- . Hold device on the tuning peg of a string.
- Pluck that string.
- . The device will use signal processing techniques to filter noise from the desired string vibration frequency.
- . Device will automatically turn a stepper motor, which winds the string's tuning peg, so that the string plays the correct frequency.

Tasks

Victor Darakjian (EE) - Signal Processing (filtering noise, frequency finding), Leading (Testing, Planning, Delegating)

Adalberto Sicairos (EE) - Hardware Implementation (sensor/motor organization and upkeep, chassis, 3D) printing)

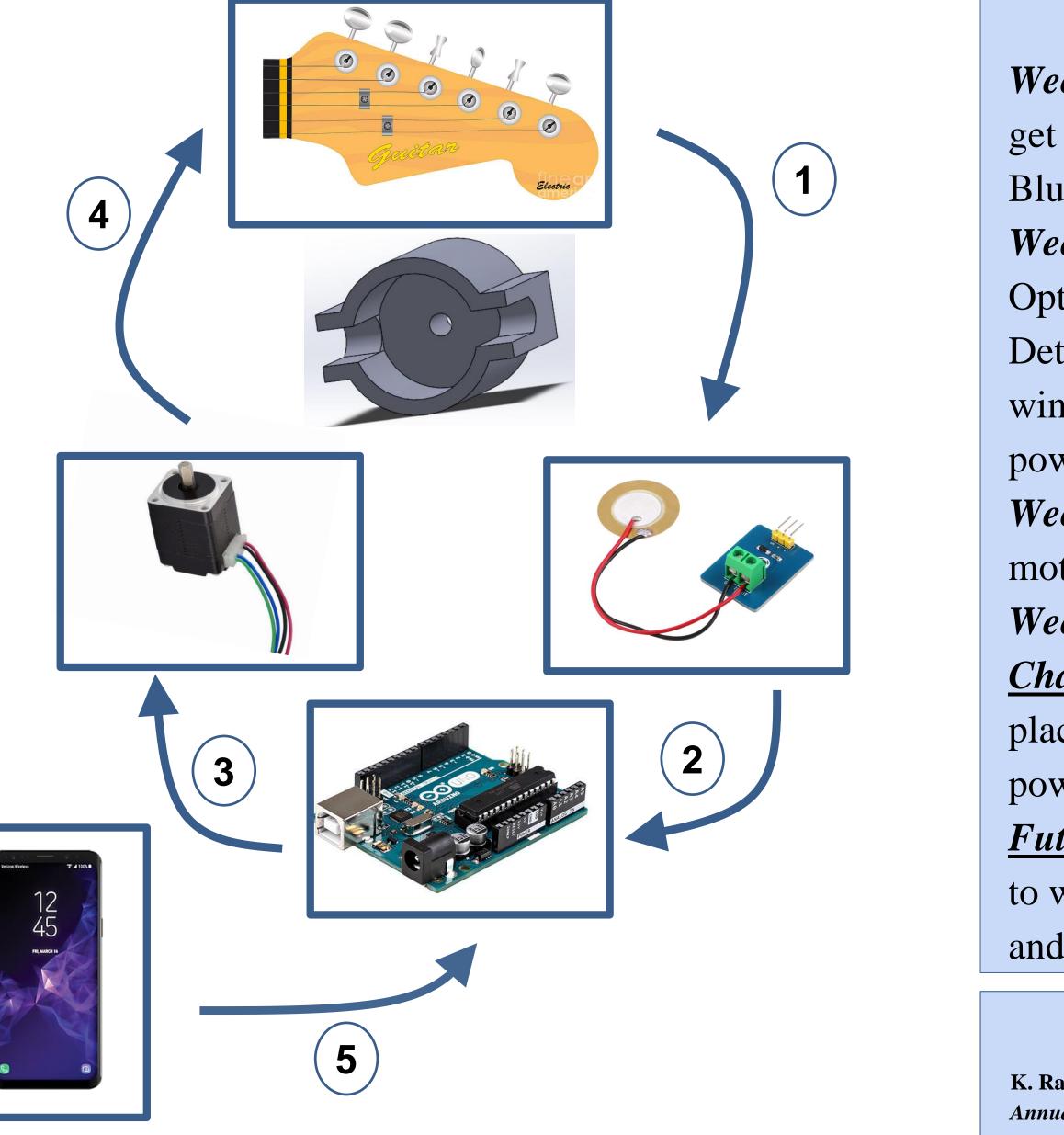
Dexter Gianto Suherman (CSE) - Microcontroller programming (sensor, motor, microcontroller)

Ha Young An (CSE) - App development

Handheld Automatic Guitar Tuner

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Components and (Conduits)

There are **5** interfaces:

- 1. Guitar-Sensor (String-winder bit)
- 2. Sensor-Microcontroller (Amplifier, Low-Pass filter)
- 3. Microcontroller-Motor (Motor Power module)
- 4. Motor-Guitar (String-winder bit)
- 5. Android App-Microcontroller (Bluetooth module)





Team GnG! (Gadgets n Gizmos)

Milestones

Week 1-3: Find an optimal sensor placement location to get reliable data. Begin creating the app and establishing Bluetooth connectivity. Learn control of stepper motor. *Week 4-7:* Reliably determine guitar string frequency. Optimize string-winding bit to transmit vibrations well. Determine a reliable ratio of frequency difference to winding rotation. Finish adding features to app. Solidify power distribution.

Week 8-9: Make the app pretty. Fine-tune any motor/sensor/algorithm features.

Week 10: Last minute checks and fixes.

<u>Challenges</u>: Figuring out an optimal vibration sensor placement for more reliable readings. Figuring out the power specs of a battery.

Future Work: Find an appropriate frequency difference to winding rotation ratio. Finish the app. 3D print chassis and solidify power distribution.

References

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