

# Autonomous Food Delivery Robot

Team members: Aakif Hussaini, Kevin Lum, Prannay Kapur, Ceyu Xu, Jingpeng Yu Professor Pramod Khargonekar

Department of Electrical Engineering and Computer Science

# Background

One of the challenges for new college students is transitioning to dining on campus. Even though colleges offer a variety of restaurants, challenges like academic stress and time management reduce the chances of students having the time to find the right food choices for them.

As a solution, the *Autonomous Food Delivery Robot* will reduce the time spent on food by removing travel time and time wasted waiting in line. Like other autonomous robots specially designed for certain tasks like interactions in the office and rescue missions, the *Autonomous Food Delivery Robot* is specialized for the UCI campus and takes advantage of how most of its restaurants are located on or near Ring Road.

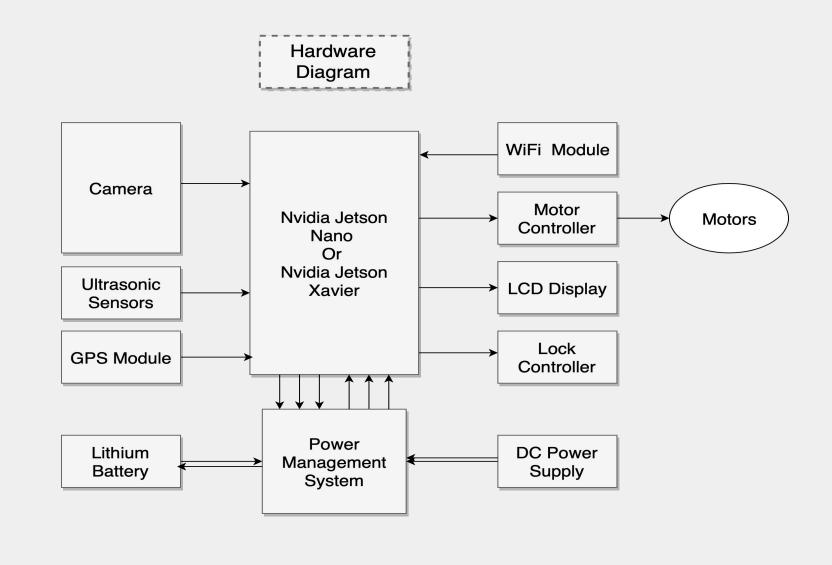
Since Ring Road is circular and accommodates vehicles, the *Autonomous Food Delivery Robot* can easily use it as a highway for food delivery and deliver more food to students in a lower amount of time. This will help reduce the cost of food delivery and offer students another option for ordering food on campus.

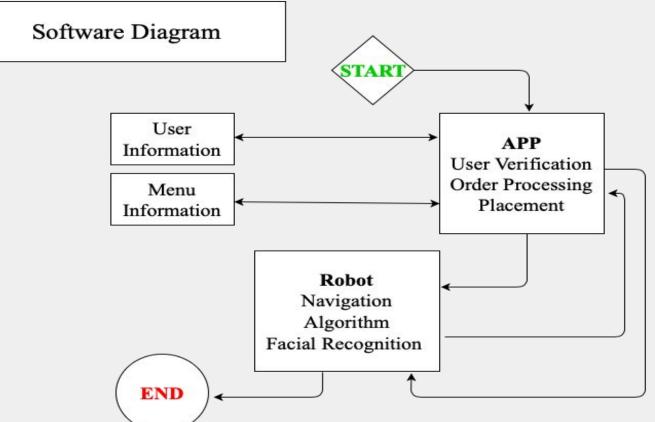
### Goals

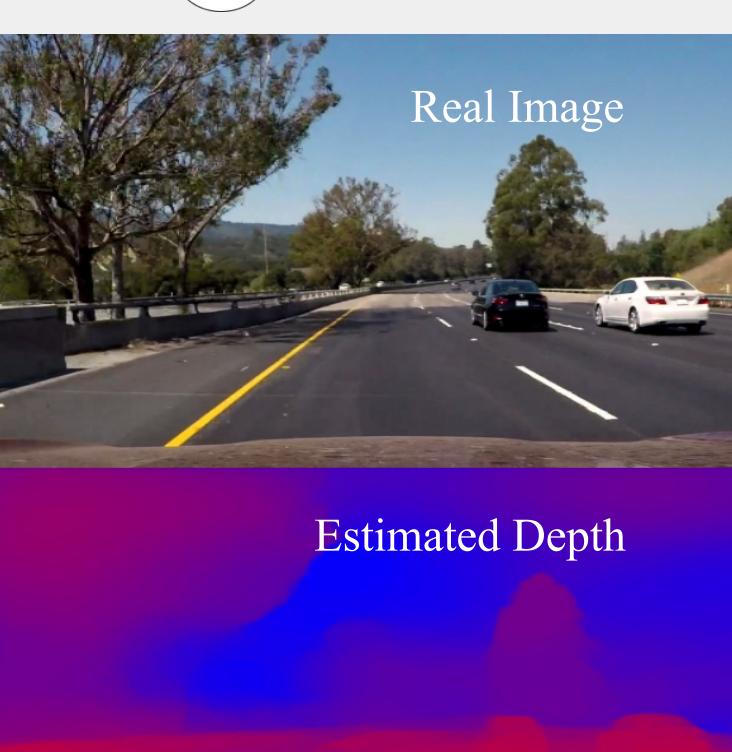
- Build a robot with a battery that lasts long enough to traverse Ring Road carrying 1kg of food.
- Create an algorithm that makes the robot go to a set destination without colliding with anything on the road.
- Build an app with a security and a management system for orders and deliveries

# Team Organization

Team Members	Responsibilities		
Aakif Hussaini	App Development	Algorithms	Fabrication
Prannay Kapur	Hardware Design	Fabrication	Robot Security
Kevin Lum	App Development	Algorithms	Hardware Design
Ceyu Xu	Algorithms	Robot Security	Fabrication
Jingpeng Yu	Database	Fabrication	Hardware Design







#### Milestones

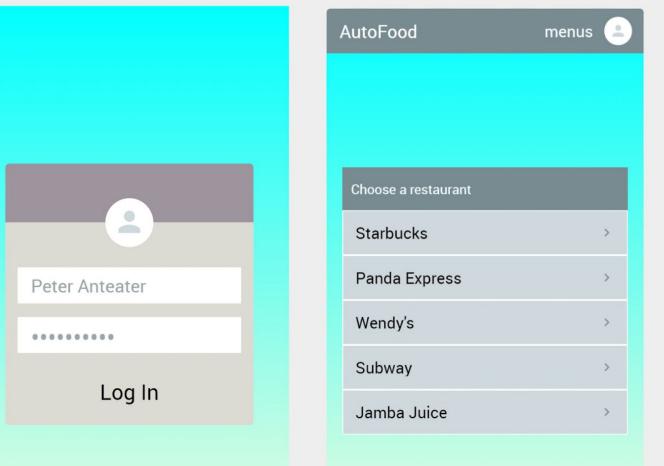
- / Developed basic object detection
- / Developed initial prototype of mobile application
- ✓ Constructed drivetrain of robot
- Began process of fabrication for food housing

## Future Work

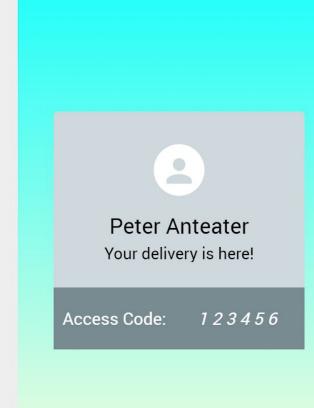
#### **Immediate Tasks:**

- Finish second prototype of mobile app
- Finish fabrication of food housing
- Test navigation and detection algorithms on kit robot
- Develop food housing's security Long-Term:
- Integrate algorithms into robot alongside mobile app functionality

#### App Layout







#### References

- J. Jean, C. Wei, Z. Lin and K. Lian, "Development of an office delivery robot with multimodal human-robot interactions," 2012 Proceedings of SICE Annual Conference (SICE), Akita, 2012, pp. 1564-1567.
- T. Okuyama, T. Gonsalves and J. Upadhay, "Autonomous Driving System based on Deep Q Learnig," 2018 International Conference on Intelligent Autonomous Systems (ICoIAS), Singapore, 2018, pp. 201-205.
- ➤ B. Doroodgar, M. Ficocelli, B. Mobedi and G. Nejat, "The search for survivors: Cooperative human-robot interaction in search and rescue environments using semi-autonomous robots," 2010 IEEE International Conference on Robotics and Automation, Anchorage, AK, 2010, pp. 2858-2863.
- X. Ye, X. Duan and H. Li, "Depth Super-Resolution with Deep Edge-Inference Network and Edge-Guided Depth Filling," 2018 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), Calgary, AB, 2018, pp. 1398-1402.

