



Project Scarecrow: A Smart Autonomous Surveillance System

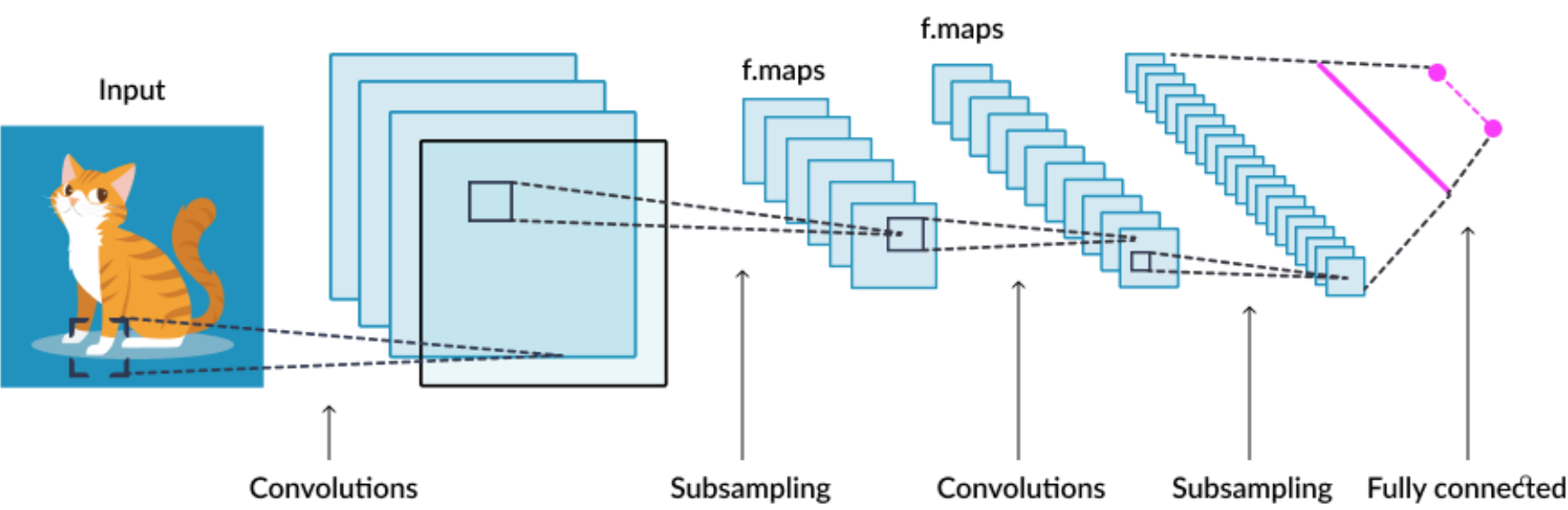
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Background

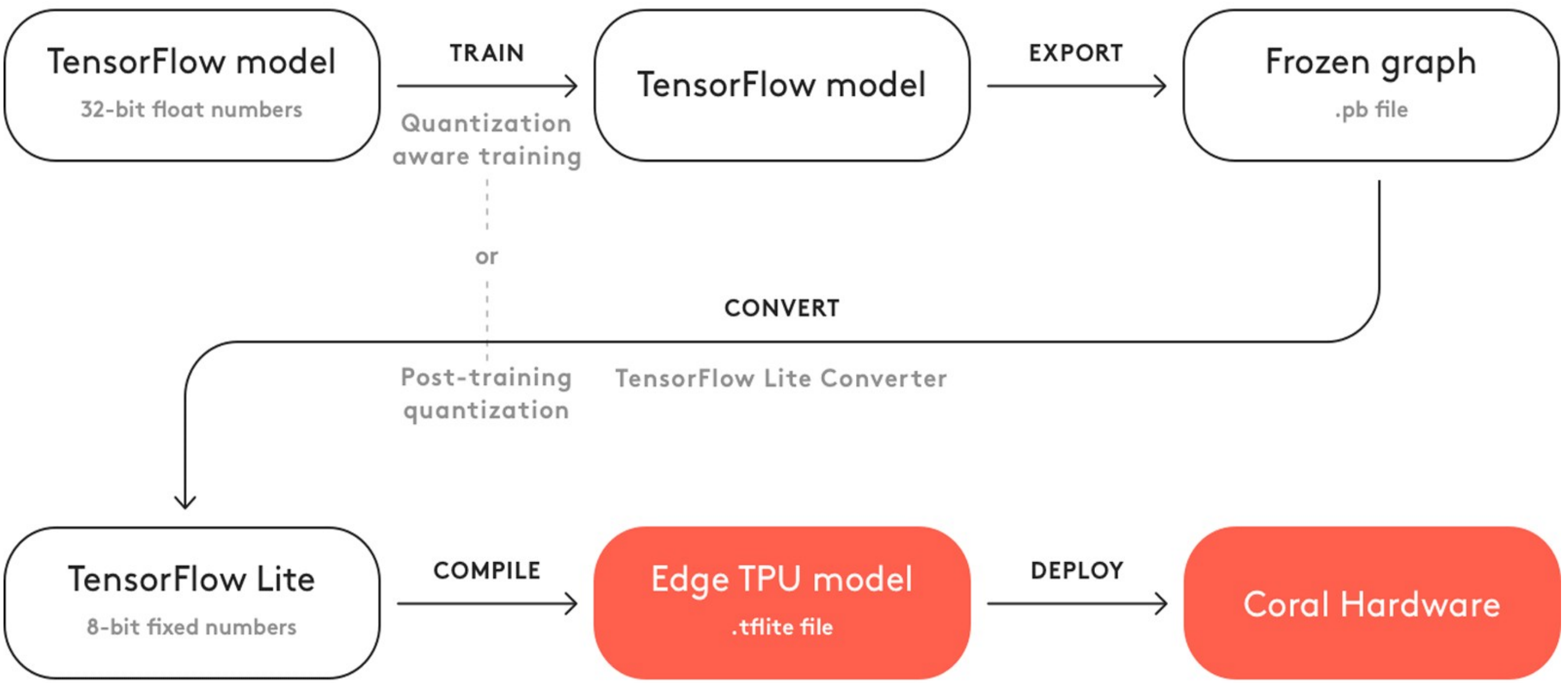
Stray animals that come in close proximity to gardens spread pathogens and ticks that harm humans, plants, and pets. Physical damages include burrowing, trampling harvest, urinating, defecating, and destroying personal property. Gardens are often where animals to congregate during mating season. Counterproductive solutions are the use of inhumane traps, pesticides, and primitive idling scarecrows.

Project Goal

- Detect, identify, and classify objects within the device’s projected proximity
- Survey an area on a low-power and low-latency standard with millisecond inference times
- Once an object is classified correctly, deter the intruder with specialized audio-animatronics
- Ensure portability and handle convolutional neural network calculations offline without a cloud



A convolutional neural network (CNN) is a multilayered system that mimics the biological neuron model. A CNN consists of an input layer, output layer, and multiple hidden layers. Each input image will pass through a series of convolution layers with filters (Kernels), pool fully connected layers (FC), and apply Softmax functions to classify an object with probabilistic values between 0 and 1.



Materials



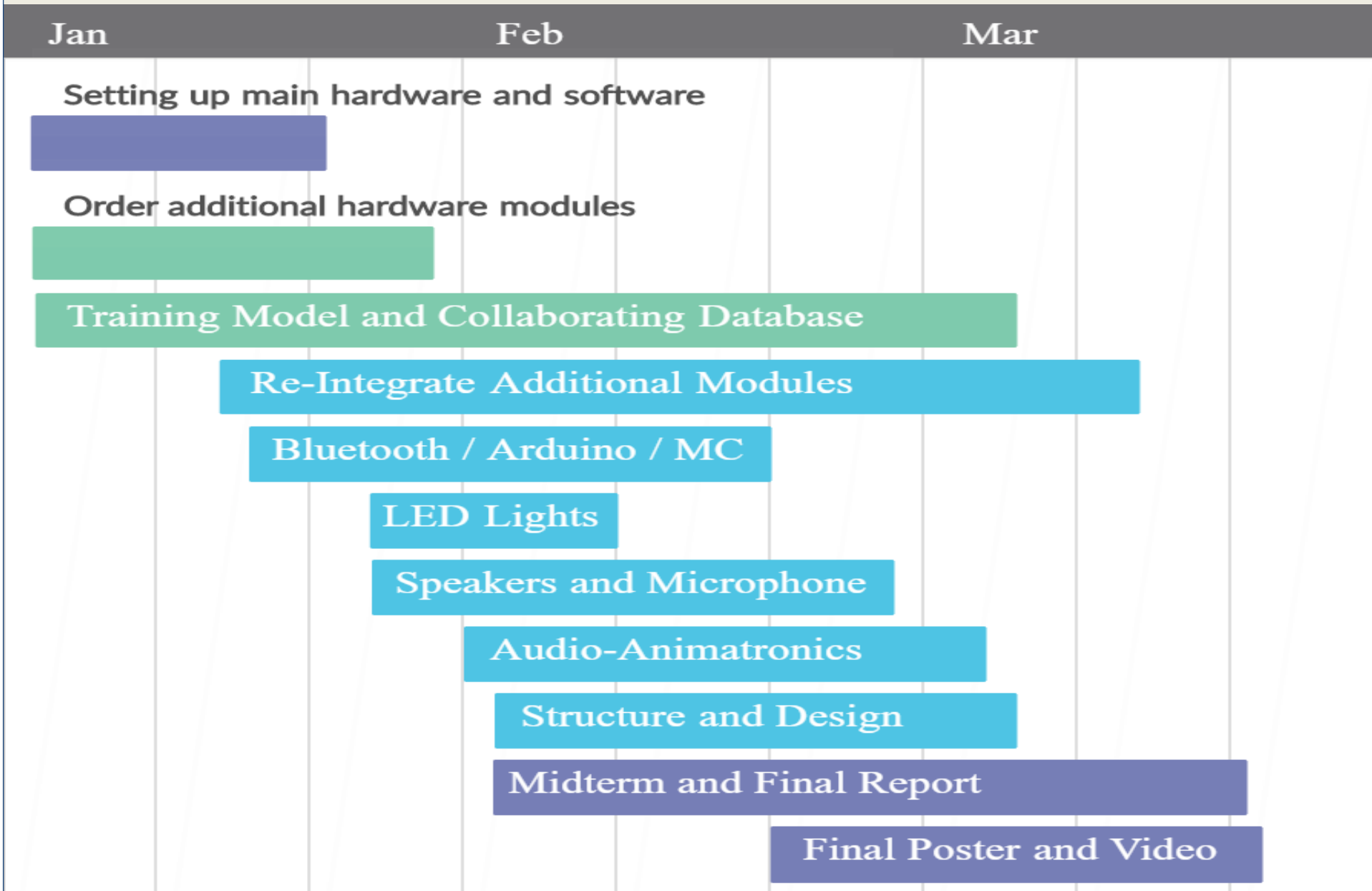
Hardware

- Google Coral Development Board
- Coral camera module
- Stepper motor(s) and driver
- Arduino Uno and Atmega32
- HM-10 Bluetooth 4.0 module
- 1W LEDs, 20W speaker

Software

- Debian Linux (Mendel 4.0)
- C, Python, Anaconda
- OpenCV and GStreamer
- TensorFlow v1.14
- Labellmg
- Solidworks and Atmel Studio

Milestones



Future Work

- Include a near-infrared camera and biosensors to monitor pollution
- Create quality audio/visual animatronics to accompany deterrent protocols
- Transfer learning by quantization-aware training
- Design and build the scarecrow structure with 3D printed models and natural materials.
- Use a video-writer to create snippet videos of animals and store them for future inspection

References

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