# **Tiltwing Electric Vertical Takeoff and Landing (eVTOL)**



## Summary

This project focuses on the design of a tiltwing eVTOL drone that combines the efficiency of fixed-wing aircraft with vertical takeoff and landing capabilities. The rotating thrust vector enable the aircraft to transitions between hover and cruise.

Figure 1 : Tiltwing eVTOL Concept Design

## **Goals and Objectives**



15-minute cruise



1-minute takeoff

1-minute landing

Figure 2: Mission Profile

# Main Constraints and Requirements

- The project budget is limited to \$600, covering both the prototype and final product.
- The project must be completed within two academic quarters.
- The total aircraft weight shall not exceed 6 lbs.

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# **Design Choice**

- efficiency



- mechanism for stable transitions
- stability and performance
- operation



### Figure 6: LS417-il Under CFD Simulation

Initial sizing is based on statistical data from similar aircraft geometry.

<u>Sizing</u>

- Aspect ratio: 6
- Wingspan: 4 ft
- Fuselage length: 3.5 ft



Figure 3: Design Size <u>Tilt-Mechanism</u>



Figure 5 : Section View of Tilt Mechanism

### Wing Airfoil Selection

LS-0417 airfoil was chosen based on trade studies for:

- Cruise Efficiency
- High lift at low speed, low angle of attack
- High stall angle



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- https://ntrs.nasa.gov/citations/20170007194 (accessed Feb.

25, 2025)