

## Executive Summary

Currently a technology gap exists in manufacturing strong magnets on the nanometer scale that have flexible characteristics. Our project will effectively solve this problem by integrating a magnetization head with a selective laser sintering (SLS) process. The magnetization head is designed to concentrate a high magnetic field strength of 1 T at the point between the tips. In addition, a rotation mount supporting the magnetization head will allow for pole patterning capabilities. Simultaneously, the diode laser will sinter the ferromagnetic polymer layer by layer in the SLS process.

## Key Features

- Magnetization Head
  - This includes the steel core, hyperco50 tips, and copper coils.
- Rotation Mount
  - This connects the magnetization head and diode laser.
  - Rotation allows for magnetic pole patterning.
- Z-Printer Gantry
  - Linear rods for motion of printing head in the x-y and z directions.
  - Roller for spreading ferromagnetic powder.
- Diode Laser
  - 10 W, 450nm, 30mm focal length.
- Control Board
  - Controls up to 8 stepper drivers with 9 stepper outputs total.
  - In coordination with Raspberry Pi.
  - Klipper Software for stepper motor actuation.

## Engineering Analysis

Utilized COMSOL Multiphysics to simulate the magnetization head and determine the location of the maximum magnetic flux density as well as the flux losses present.

- Simulation Specifications
  - 10 A, 1000 Turns of Coil, 20 mm Coil Length, 1 mm Air Gap Length
- Material Properties
  - Magnetic Core: 1008 Low Carbon Steel
  - Magnetic Tips: 1008 Low Carbon Steel (Hyperco50 to be used once the relative permeability is known)
- Results
  - Maximum magnetic flux density of 1.3 T at 1mm below surface of tips.
  - Large magnetic flux density leaks at bends along tip distance.

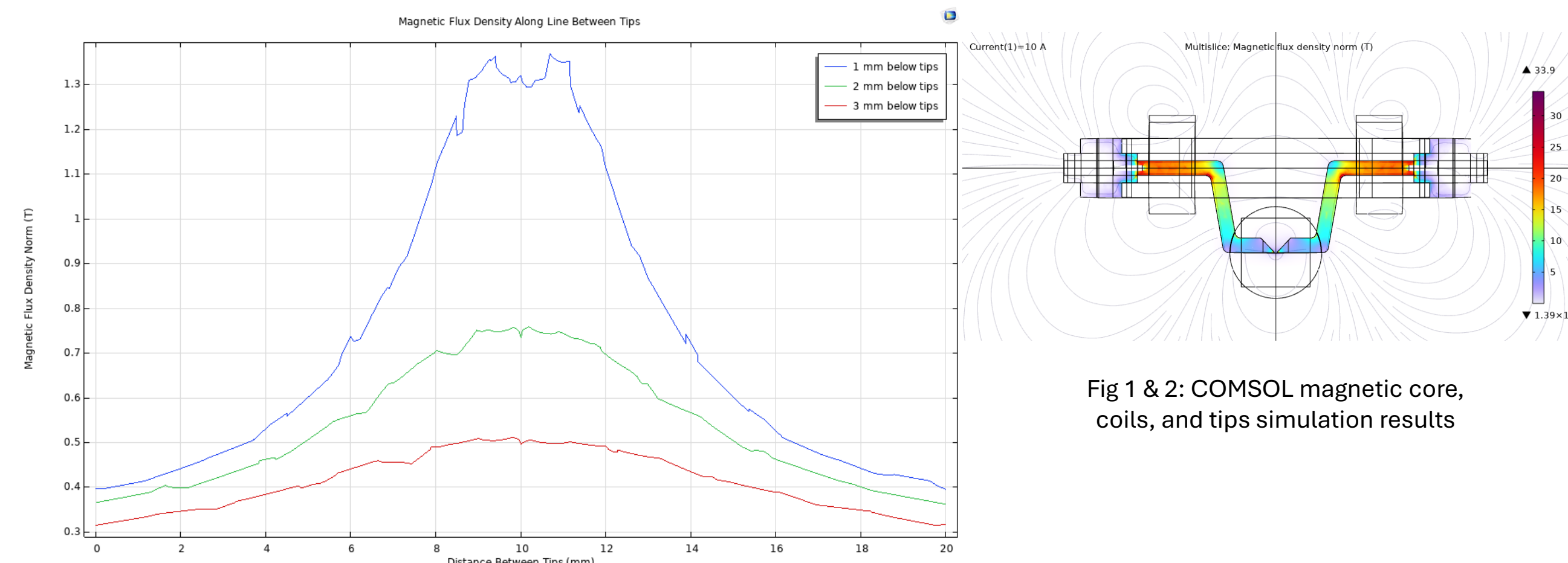


Fig 1 & 2: COMSOL magnetic core, coils, and tips simulation results

## Future Improvements

- Fine tuned z-axis motion by stepper motors.
- Alter Z-Printer bed to have smaller build volume.
- Allow for easy adjustment of tip height from bed.

## Team Contributions

MAE151A

- Simulations, CAD modeling, magnetic circuit calculations, 3D printing, electrical circuits, motor testing, and developing stakeholder needs and expectations.

MAE151B

- CAD modeling, Z-Corp printer deconstruction and integration, new controller-motor testing,

## Impact and Considerations

Impact

- Due to being sponsored by the US Army Research Lab, applications such as magnetic drone charging.

- On a broader scale, this project enables the fabrication of intricate magnetic structures with greater precision and flexibility.

- Conventional magnet production involves significant material wastage due to subtractive machining methods. SLS reduces material loss, making the process more eco-friendly and cost-effective.

Consideration

- Magnetic properties of the printed magnets need to be tested and compared to traditionally manufactured magnets.

## Acknowledgements

Thank you to our sponsor Professor Camilo Cuervo and graduate students Naji Tarabay and Mahtab Shakibmanesh for your support throughout the process of this project.

## Overview

### Full CAD Design

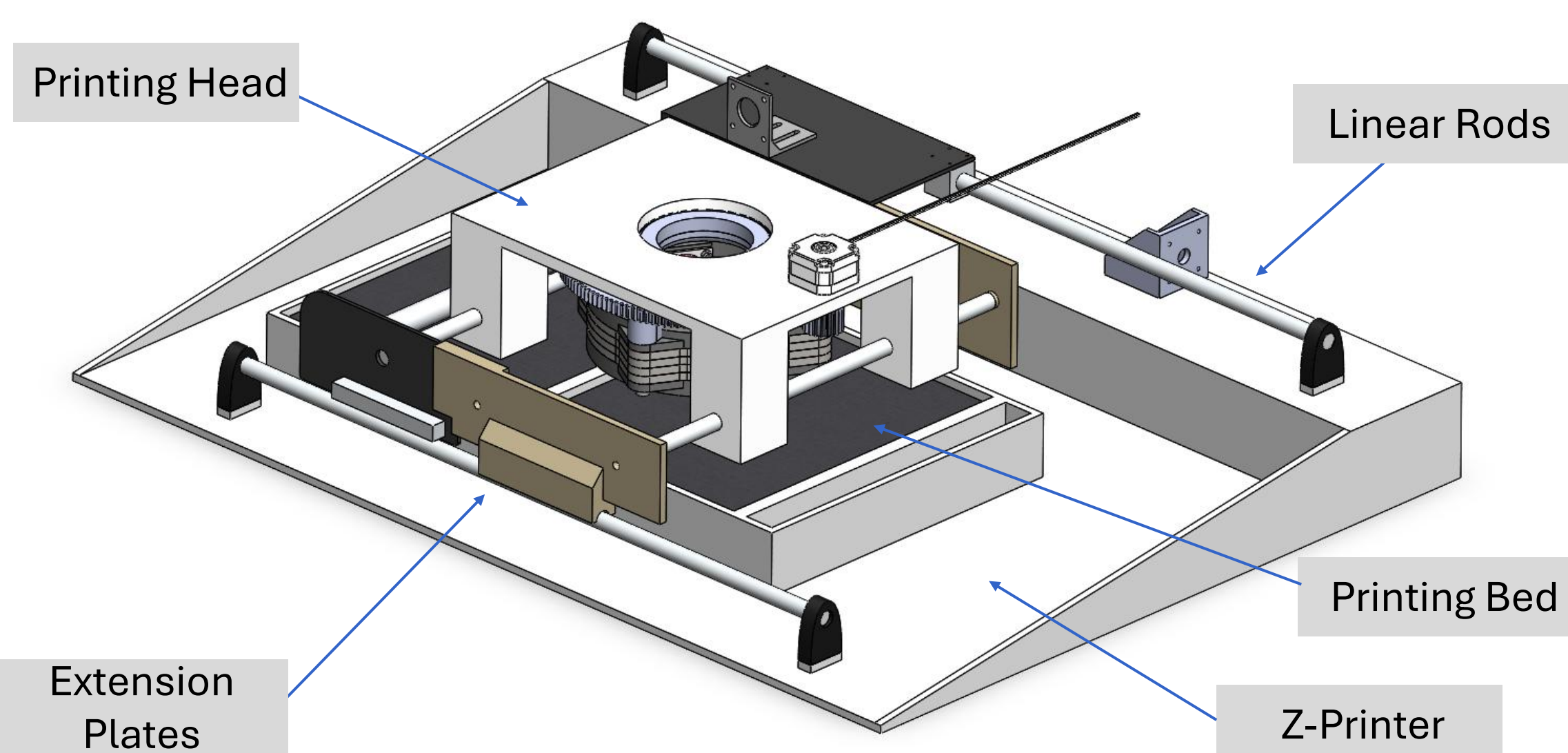


Fig 3: Complete model of rotational gantry and magnetic core within a model of the Z-Corp printer

### Rotation Gantry CAD

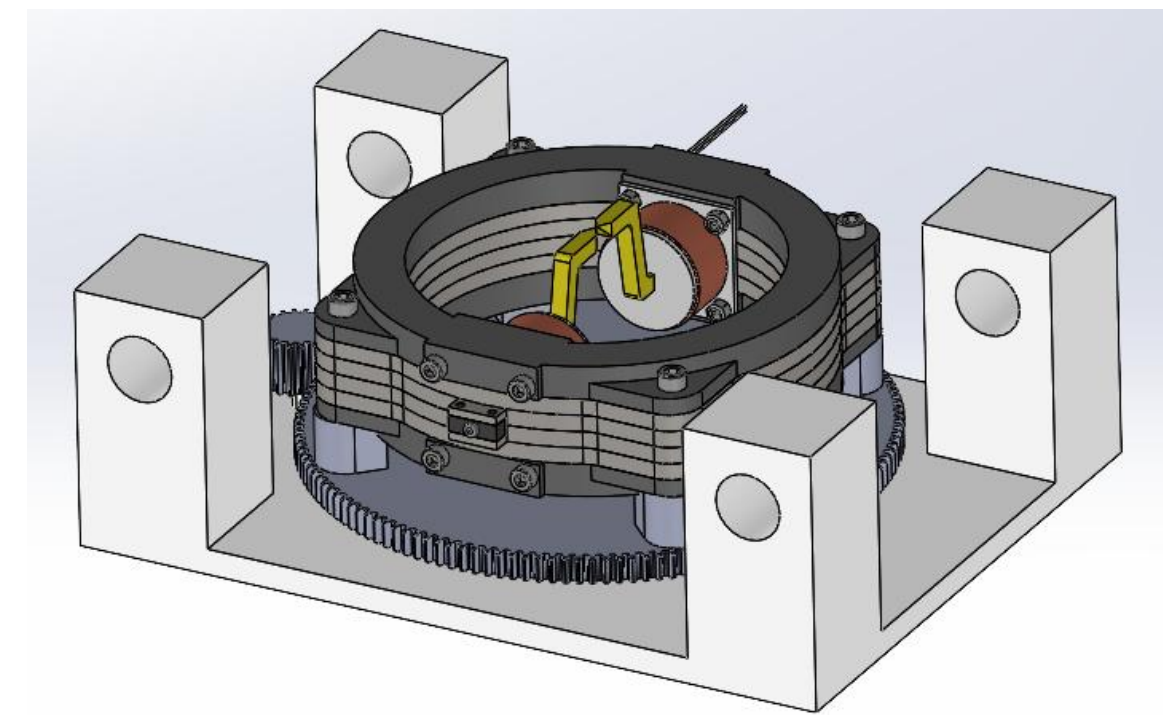


Fig 4: Inverted image of rotation mount and magnetization head connection model

### Magnetization Head CAD

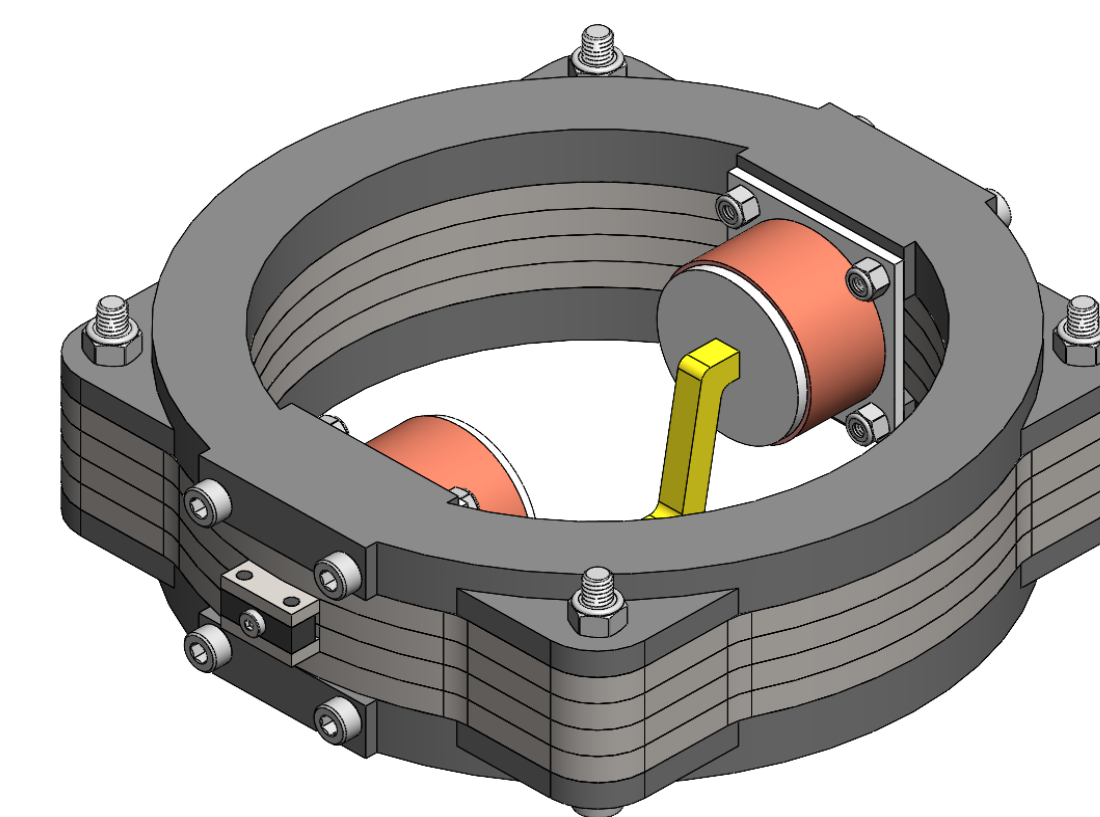


Fig 5: Magnetic circuit model (core, coils, and tips)