

Department of Mechanical and Aerospace Engineering

Astrobotics

ASTRONICS

Team: Jose Pereida, Nick Karp, Griffith Wagner, Hamid Sharifinejad, Frank Vu, Christopher Khacerian, Nick Oune Company Liaisons: Jesse Gillespie, Lee Wu, Susan Moran

Faculty Advisors: Dr. Vince Mcdonell, Dr. Farzad Ahmadknanlou

Design safety barriers to protect workers





Background

Astronics Test Systems has developed a semiconductor test system, the Single Slot Tester (SST), to meet the demand of low throughput test systems in industry. However, the current SST requires a technician to individually place DUT's (Device Under Test) into the BIB (Burn In Board) from the JEDEC tray and vise versa. This results in hours of medial work. As a result, the goal of this project is to integrate Astronic's existing SST with a FANUC six axis robot to fully automate the testing process.

Fall Quarter: Hardware Development

Week 1:
Determination of
Hardware
Requirements

Weeks 2-3:
Hardware
Conceptualization
and Solutions

Week 4:
Down Selection and
Preliminary Design
Development

Week 5: Present Progress to Astronics

Week 6-8:
Hardware Design
Refinements;
Complete Bill of
Materials

Week 9-10:
Order Materials for Proof
of Concept;
Determination of
Software Requirements

Winter Quarter: Software Integration

Week 1-2:
Build Workstation;
Program General
Robotic Movements

Weeks 3-4:
Integrate & Refine
Robot Programming
& Workstation

Week 5:
Present Progress
to Astronics

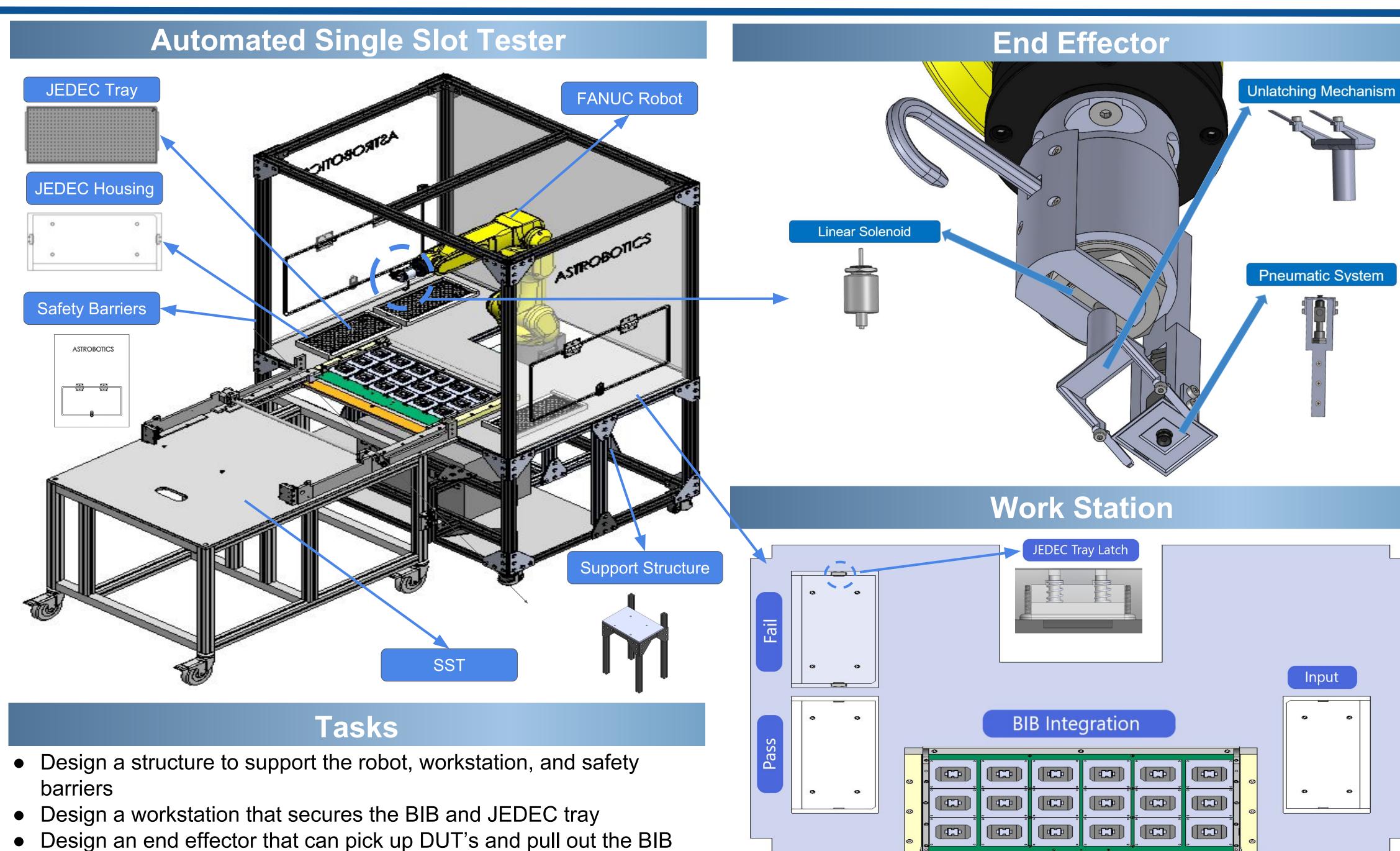
Week 6-8:
Program User
Interface

Week 8-10:
Integrate IR Vision
into Robot
Programming

Week 10:
Automated SST
Complete and
Working

Contact Information

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Robot Logic

