

## Design Constraints

The design of the sprayer should be such that it will:

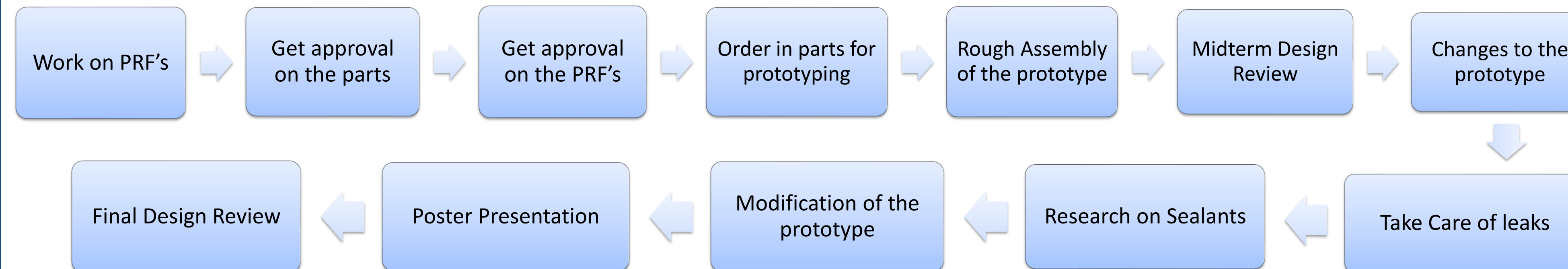
- Provide 30 PSI targeted IPA spray
- 1 meter insertion depth
- Waterproof and chemical resistant
- Maximum 2 mm diameter
- Singled handed operation
- Ergonomic
- Redundant safety system
- Spark proof electronics/mechanics
- \$500-\$1000 budget



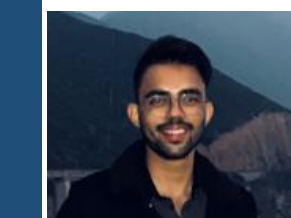
## Purpose of the Device

The purpose of this project is to create a flexible isopropyl alcohol (IPA) sprayer to navigate through complex geometries of 3D printed components and to fully coat it with IPA. Our task is to check for foreign object debris (FOD). It will be done by going inside of these parts, spraying IPA, and then going through an inspection process to check for cleanliness.

## Project Timeline: Winter 2022



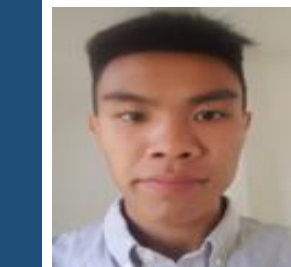
## Team Roster



Rishabh Bhushan



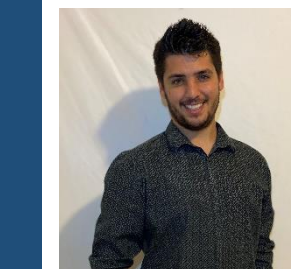
Ognjen Cosic



Daniel C. Lai



Alexis Fuentes-A

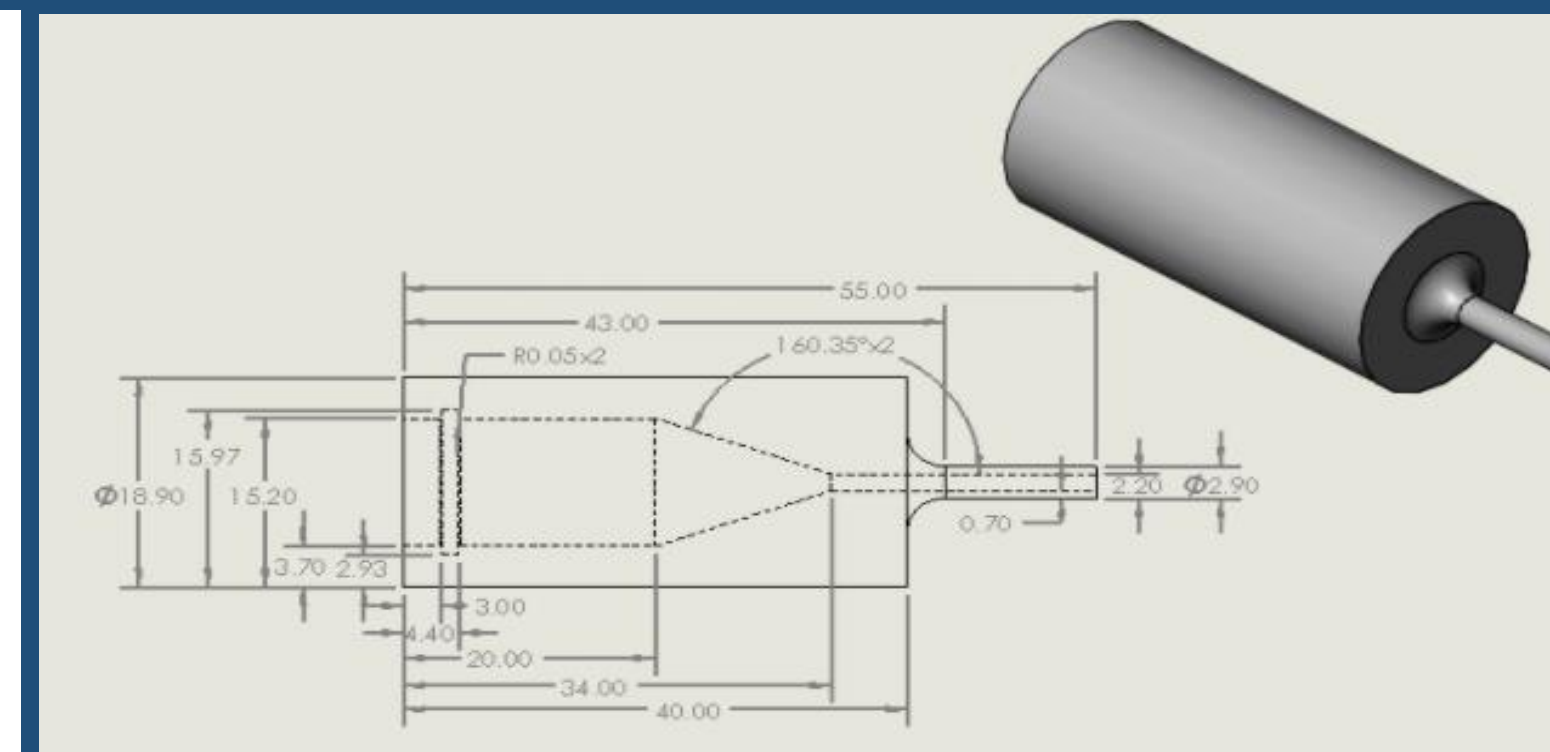
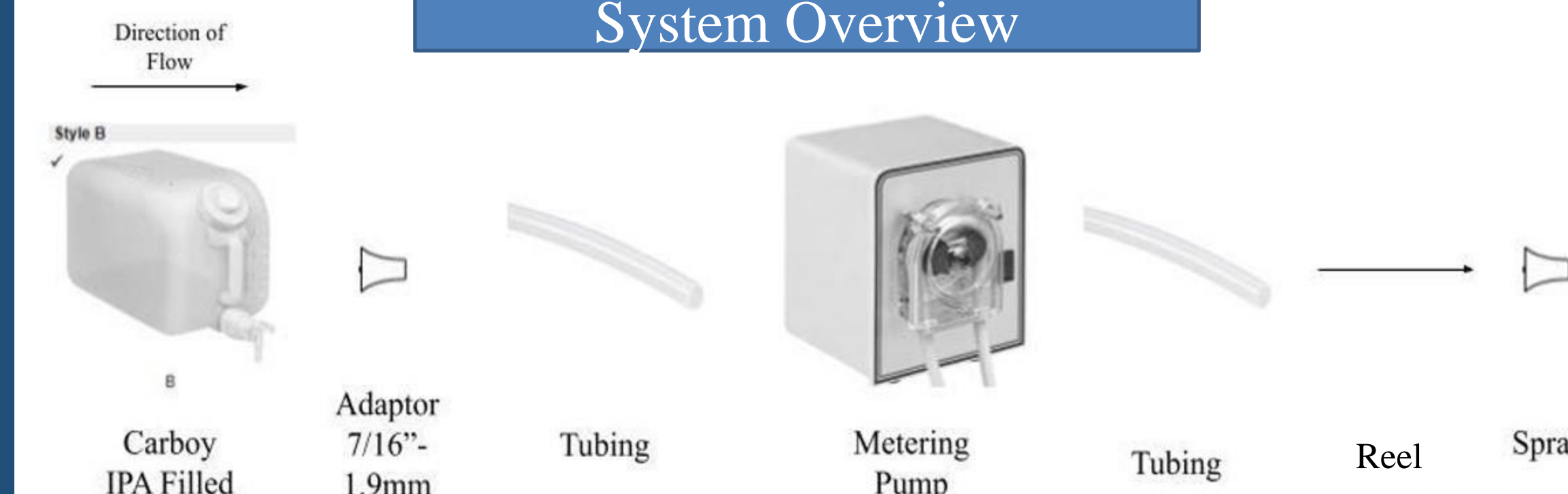


Kameron Cole Ziff

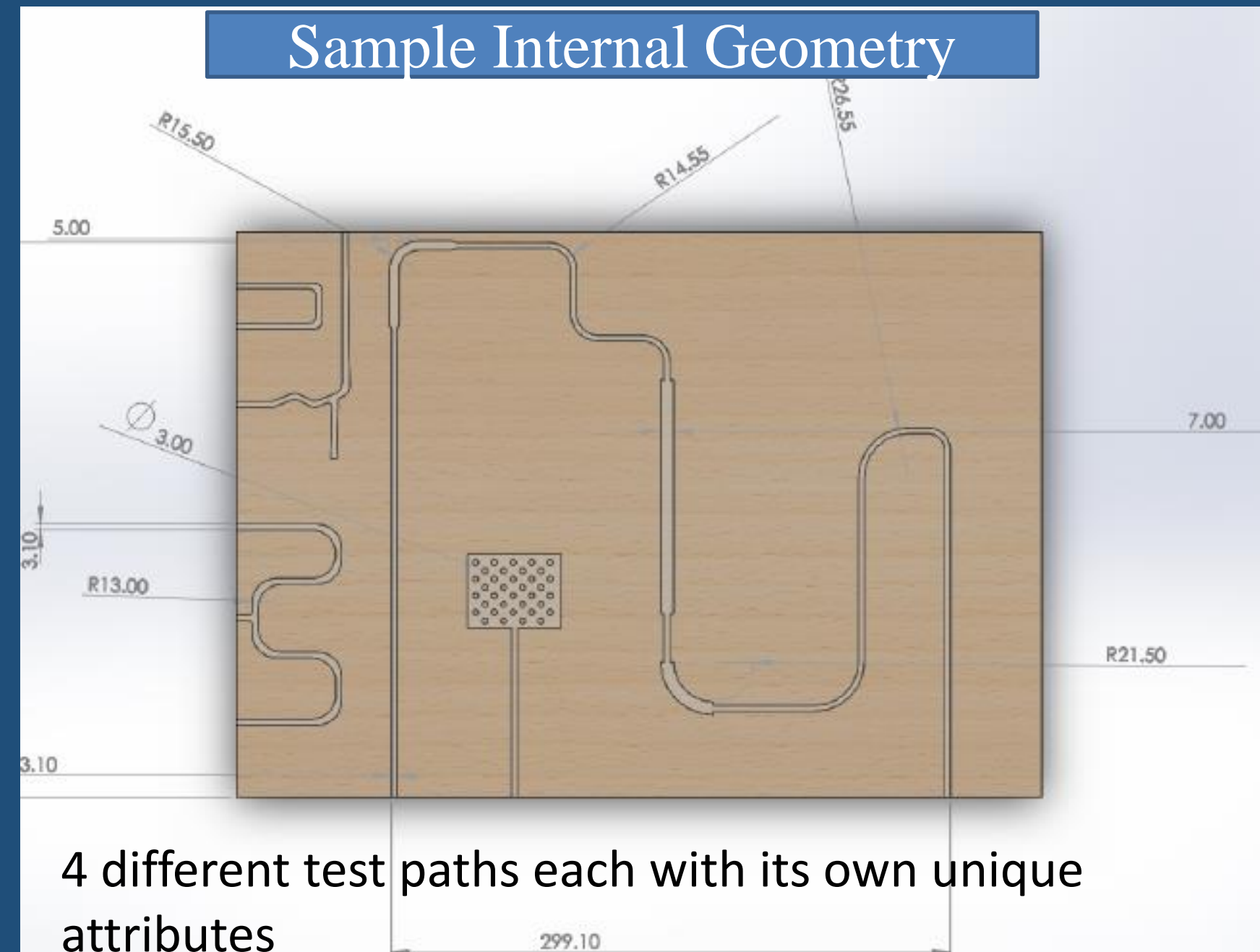
## Solution

Our primary objective is to coat the internal geometry with IPA as efficiently as possible. We want this product to be user friendly and highly effective. After going through an exhaustive design selection process, our team has finalized on an idea inspired from a drain snake. We will feed in a tube manually where the IPA flow will be powered through a pump.

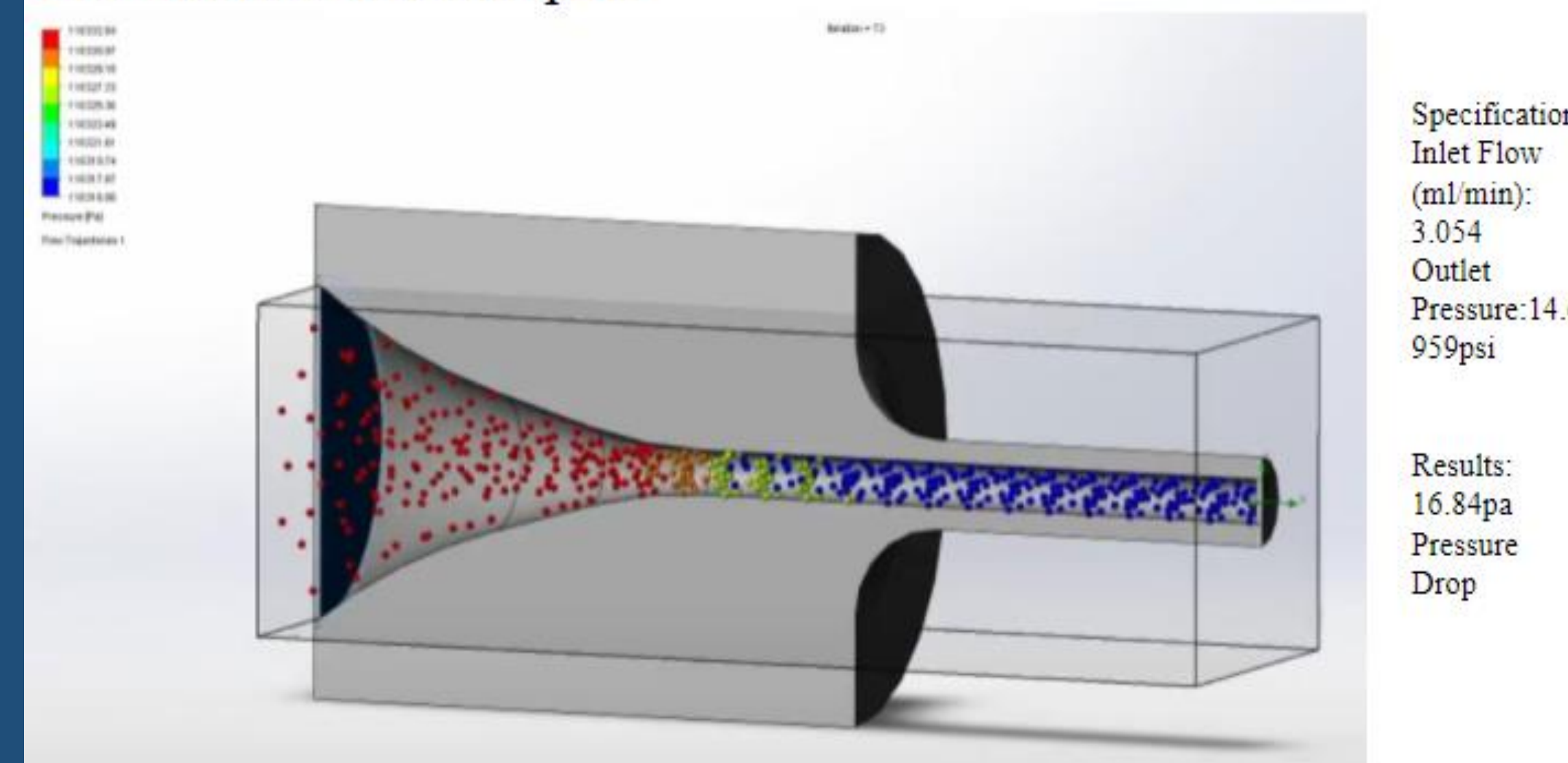
## System Overview



## Sample Internal Geometry



## CFD for the Tube Adaptor



## Overview of Supplies

